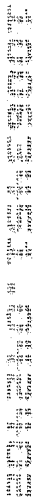


[illegible]

**FIG. 2**

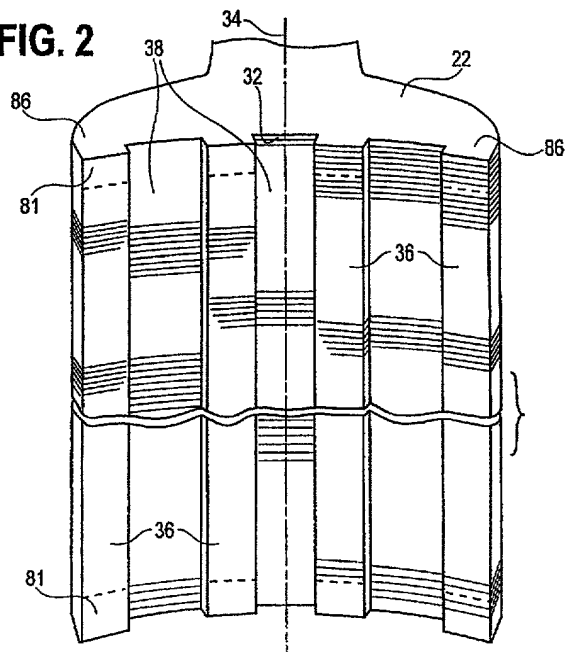


FIG. 3A

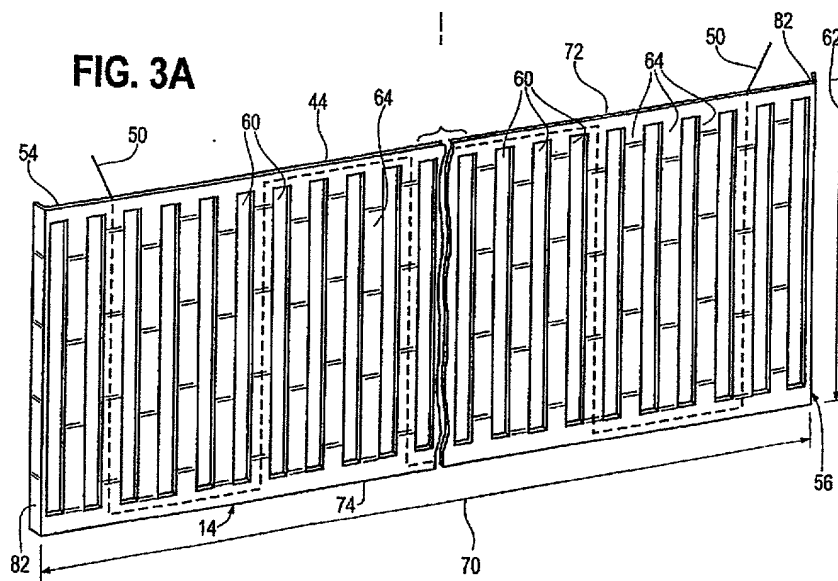


FIG. 3B

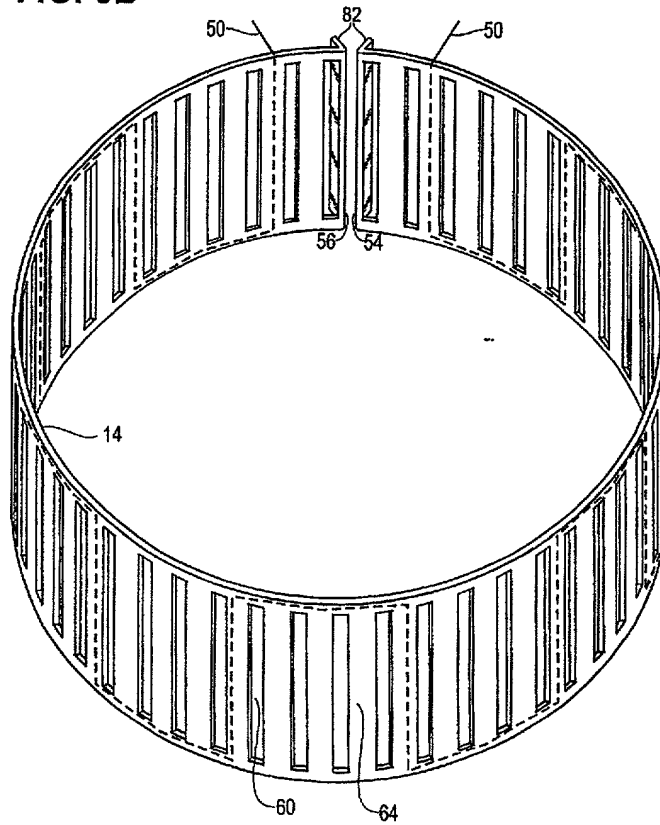
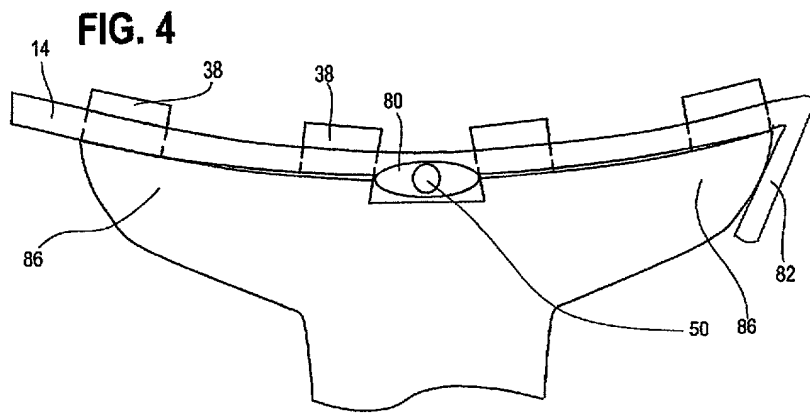
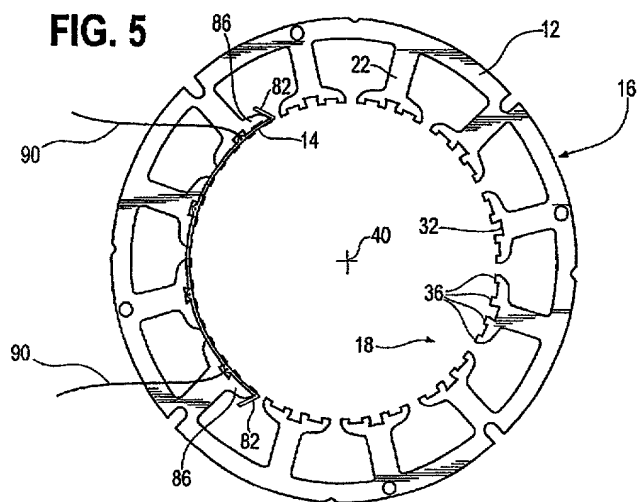
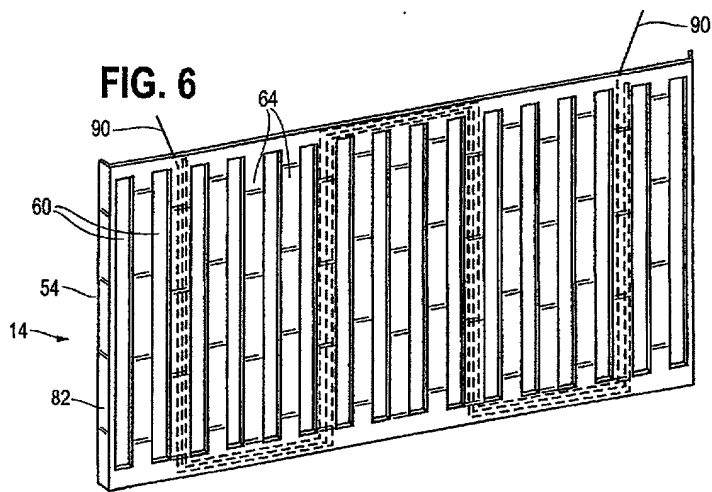


FIG. 4 is a perspective view of the device 10 in a closed position. The device 10 includes a main body 14 and a handle 16. The main body 14 is formed of a material that is resilient and flexible. The handle 16 is formed of a material that is rigid and strong. The device 10 is configured to be used for holding and gripping objects. The device 10 is shown in a closed position, where the main body 14 is folded back towards the handle 16. The device 10 is shown in a perspective view, which allows for a three-dimensional representation of the device. The device 10 is shown in a simplified manner, without any unnecessary details. The device 10 is shown in a clear and concise manner, which allows for a better understanding of its structure and function. The device 10 is shown in a perspective view, which allows for a three-dimensional representation of the device. The device 10 is shown in a simplified manner, without any unnecessary details. The device 10 is shown in a clear and concise manner, which allows for a better understanding of its structure and function.



**FIG. 5**





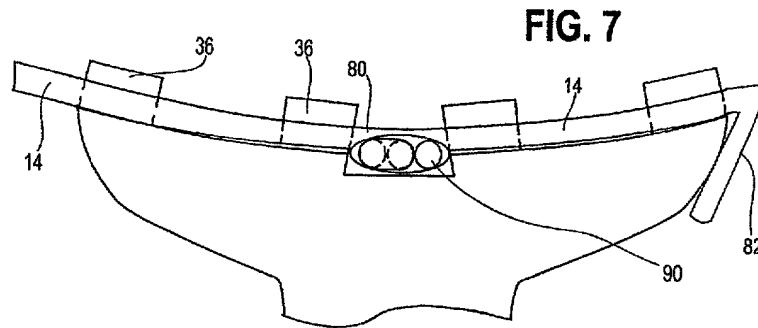


FIG. 7 is a schematic diagram of a curved structural member, possibly a beam or a part of a machine. The member is labeled 14 and is shown in a curved, cross-sectional view. It features several rectangular blocks or components labeled 36, which are positioned along its length. A central component is labeled 80, and it contains three circular elements. A line labeled 90 points to the lower, curved portion of the member. On the right side, a component labeled 82 is shown, which appears to be a support or a connection point. The diagram is enclosed in a rectangular frame.